LMM-R1: Empowering 3B LMMs with Strong Reasoning Abilities Through Two-Stage Rule-Based RL

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https://github.com/username/LMM-R1

Abstract

Enhancing reasoning in Large Multimodal Models (LMMs) faces unique challenges from the complex interplay between visual perception and logical reasoning, particularly in compact 3B-parameter architectures where architectural constraints limit reasoning capacity and modality alignment. While rule-based reinforcement learning (RL) excels in text-only domains, its multimodal extension confronts two critical barriers: (1) data limitations due to ambiguous answers and scarce complex reasoning examples, and (2) degraded foundational reasoning induced by multimodal pretraining. To address these challenges, we propose LMM-**R1**, a two-stage framework adapting rule-based RL for multimodal reasoning through Foundational Reasoning Enhancement (FRE) followed by Multimodal Generalization **Training (MGT)**. The FRE stage first strengthens reasoning abilities using text-only data with rule-based RL, then the MGT stage generalizes these reasoning capabilities to multimodal domains. Experiments on Qwen2.5-VL-Instruct-3B demonstrate that LMM-R1 achieves 4.83% and 4.5% average improvements over baselines in multimodal and textonly benchmarks, respectively, with a 3.63% gain in complex Football Game tasks. These results validate that textbased reasoning enhancement enables effective multimodal generalization, offering a data-efficient paradigm that bypasses costly high-quality multimodal training data.

1. Introduction

Recent years have witnessed remarkable progress in Large Language Reasoning Models (LLRMs) [22, 55, 71]. Re-



Figure 1. Comparison of reasoning approaches on a geometric problem. The baseline LMM (top) incorrectly identifies the slant height, leading to an erroneous solution. In contrast, LMM-R1 (bottom) demonstrates superior reasoning by correctly applying the Pythagorean theorem to determine the actual slant height, showcasing how our rule-based RL approach enhances the model's ability to apply proper mathematical principles.

searchers have explored approaches like Monte Carlo Tree Search (MCTS) [48, 84, 85] and Process Reward Models (PRM) [36, 48, 62], which require extensive human annotation [36] or expensive computational resources [48, 76, 84]. DeepSeek-R1 [22] introduced a more efficient approach with Rule-based Reinforcement Learning (RL), which only requires prompt-answer pairs, enabling models to autonomously improve reasoning through exploration while avoiding reward hacking [22]. When we turn our attention to the multimodal domain, the challenges of enhanc-

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Figure 2. The top shows that LMM-R1 uses a two-stage, rule-based RL strategy to enhance reasoning capabilities. The first Foundational Reasoning Enhancement (FRE) stage trains LMM using text-only reasoning data to improve its foundational reasoning skills. Subsequently, the second Multimodal Generalization Training (MGT) stage then extends these capabilities across diverse multimodal domains, with evaluation benchmarks illustrated in the bottom panel.

ing reasoning capabilities become considerably more complex. Large Multimodal Models (LMMs) face greater challenges as visual information increases reasoning complexity by requiring integration of both visual perception and logical reasoning. This challenge is particularly severe for 3B LMMs, as their limited parameter capacity constrains their capabilities. Moreover, such requirement makes highquality multimodal reasoning data extremely difficult to collect [79], further complicating the use of multimodal data with reasoning processes for training [24, 75, 93].

Given rule-based RL's potential in the text-only domain [49, 89], we aim to extend it to multimodal reasoning. However, direct application faces two specific issues: (1) Data limitations: Rule-based RL requires uniquely verifiable answers for accurate rewards, yet multimodal tasks often involve answer ambiguity (e.g., image description, visual QA), while also suffering from an abundance of perception-focused data but limited complex reasoning examples, which may lead to insufficient reasoning in RL; (2) Weak foundational reasoning: Models trained on multimodal data often show weakened capabilities on text-only tasks [37], and some LMMs using Chain-of-Thought (CoT) actually experience performance degradation on multimodal benchmarks [16, 82], a phenomenon amplified in smaller 3B-parameter architectures due to their limited capacity.

To address these challenges, we propose a simple

yet effective two-stage rule-based RL training framework: LMM-R1, aimed at enhancing the general reasoning capabilities of LMMs. While previous studies suggest that the smaller 3B LMM inherently lacks the capacity for complex multimodal reasoning, we demonstrate that strategic two-stage training can overcome these architectural constraints. As shown in Fig. 1, LMM-R1 correctly applies the Pythagorean theorem to determine the slant height of the cone, while the baseline LMM incorrectly identifies it, demonstrating how our approach enhances mathematical reasoning capabilities. Our framework consists of two key stages. The first stage is Foundational Reasoning Enhancement (FRE), which uses rule-based RL with abundant high-quality text-only data to strengthen the model's basic reasoning abilities. This stage establishes a solid reasoning foundation that serves as a crucial stepping stone for subsequent multimodal generalization, avoiding the need for expensive multimodal data. The second stage is Multimodal Generalization Training (MGT), where we continue rule-based RL training on limited complex multimodal reasoning tasks. This continuing training generalizes the reasoning abilities to various multimodal domains. In the MGT stage, we focus on two key multimodal reasoning domains: general multimodal reasoning domain and agentrelated reasoning domain. For general multimodal reasoning domain, we further extend the model's reasoning abilities to various multimodal scenarios including GeoQA, ScienceQA, and ChartVQA, etc.

For the agent-related domain, which represent significant real-world use cases of LMMs [42, 74], we evaluate our approach on tasks such as Sokoban [58] and football tasks [30]. These tasks require sophisticated reasoning skills, including goal identification, path planning, and multi-image processing, thus provide meaningful assessments of real-world applications. Besides, continuing training the model on Sokoban with rule-based RL further improves its performance on the agent-related benchmark, further validating LMM-R1's effectiveness in agent domains.

In experiments, we use Qwen2.5-VL-Instruct-3B [6] as the baseline model and apply LMM-R1 on it and the results reveal several important findings. First, enhancing foundational reasoning capabilities is crucial for multimodal reasoning. Using text-only data for RL training can significantly improve the multimodal reasoning capabilities both in general domain and agent-related domain, while directly using multimodal data for rule-based RL yields limited improvement in reasoning abilities. As shown in Fig. 2, our experiments reveal that the model fails to generate highquality long reasoning processes after directly trained on verifiable multimodal data with rule-base RL. Furthermore, LMM-R1 not only enhances the model's reasoning capabilities but also further improves its visual abilities. Specifically, LMM-R1 achieves significant performance improvements across multiple multimodal benchmarks, such as a 4.5%/4.83%/3.63% performance increase over the baseline model on the text-only/five multimodal/ Football Game benchmarks. Our main contributions include:

- We introduce LMM-R1, the first framework using rulebased RL with a two-stage training strategy (FRE and MGT) to enhance multimodal reasoning without extensive human annotation.
- We show that using text-only reasoning data through rulebased RL can largely improve the foundational reasoning ability and more importantly, such ability can be generalized to multimodal domains.
- We demonstrate that even for a 3B LMMs which initially possess very limited reasoning capabilities, LMM-R1 can significant enhance the reasoning ability, suggesting the vast potential of LMM-R1 for broader applications.

2. Related Work

Large Multimodal Model (LMM). LMMs integrate additional modalities, particularly vision, into Large Language Models (LLMs) [1, 4, 17, 73] to enhance general vision capabilities. Initially, models like Flamingo [3] and BLIP-2 [33] aligned frozen vision encoders with LLMs for visual question answering. Subsequently, the LLaVA series [39– 41], MiniGPT-4 [96], and mPLUG-Owl series [86–88] introduced visual instruction tuning to improve instructionfollowing. Models such as VisionLLM [78], KOSMOS- 2 [57], Shikra [11], and the Qwen-VL series [5, 6, 77] enhanced LMMs with visual grounding for tasks like region description and localization. InternVL [15] scaled up vision foundation models for alignment with LLMs. Additionally, GPT-4V [54] and Gemini [68] demonstrated strong general visual understanding. Mixture-of-Experts (MoE) approaches improved understanding in DeepSeek-VL2 [81], Uni-MoE [34], MoVA [97], and MoME [63]. Some models, including SEED-X [20], Chameleon [67], Show-o [83], Transfusion [95], and Janus [14, 80], unified vision understanding and generation. However, most existing LMMs still lack reasoning capabilities.

Reinforcement Learning in LLMs and LMMs. Reinforcement Learning (RL) has become a key methodology for enhancing the capabilities of LLMs and LMMs. Early research primarily focused on Reinforcement Learning from Human Feedback (RLHF) [56], which aimed to align model outputs with human preferences [7, 56, 66]. Recent advancements have demonstrated that RL can significantly enhance the reasoning capabilities of these models. For instance, models such as DeepSeek-R1 [22] and Kimi-1.5 [69] highlight the effectiveness of RL in improving LLMs' reasoning abilities through rule-based reward. In the multimodal domain, research on leveraging RL to enhance LMMs' reasoning capacities remains in its early stages. Some researchers [50, 82] explore using Process Reward Models (PRM) to enhance the LMMs' reasoning capabilities. However, these PRM-based approaches typically require powerful closed-source models to generate large amounts of training data, resulting in high computational and financial costs. Concurrent work R1-V [13] explores rule-based RL in specific subdomains such as geometry problems and object counting tasks, but lacks exploration in general domains and agent-related applications.

3. Preliminaries

3.1. Reinforcement Learning for LMMs

We use the Proximal Policy Optimization (PPO) algorithm [60] to train the LMMs, which aims to maximize the following objective function:

 $\mathcal{L}(\theta) = \mathbb{E}_{y \sim \pi_{\theta}}[r(y) - \beta \cdot \text{KL}(\pi_{\theta}(y|\mathcal{I}, x)) | |\pi_{\theta_0}(y|\mathcal{I}, x))], (1)$ where *y* is the generated answer, \mathcal{I} is the image input (if any), *x* is the text prompt, π_{θ} is the policy model, π_{θ_0} is the fixed initial policy, and β is the Kullback-Leibler divergence (KL) penalty coefficient.

3.2. Reward Function

We follow [22] in designing a two-part reward function for rule-based RL:

Format Reward. We first evaluate whether the responses follow the required structured format, *i.e.*, wrapping the reasoning within <think></think> tags, followed by the

final answer in <answer></answer> tags. This format encourages the model to explicitly demonstrate its reasoning process before providing the final answer, which is crucial for readability and evaluating the reasoning quality.

Accuracy Reward. The second metric evaluates the correctness of the solution. We employ a symbolic verification approach [76] that parses both the model's answer and the ground-truth solution into comparable representations. These representations are then checked for equivalence rather than exact string matching, allowing for different but equivalent expressions to be recognized as correct.

The final reward function r(y) can be described simply as follows: $r(y) = \alpha \cdot r_f(y) + r_a(y)$. Here, $r_f(y)$ is the format reward, and $r_a(y)$ is the accuracy reward. The parameter α adjusts how important the format is compared with the accuracy. This reward function can effectively guide the model not only to produce correct solutions, but also to articulate its reasoning process in a structured manner.

4. LMM-R1: Two-Stage Rule-based RL

Inspired by the approach used to develop DeepSeek-R1 from DeepSeek-R1-Zero [22], we divide our multimodal reasoning model training into two stages: (1) Increase the model's foundational reasoning ability with rule-based RL using high-quality text-only; (2) Generalize reasoning ability across three distinct and complex multimodal reasoning tasks independently.

4.1. Foundational Reasoning Enhancement (FRE)

To enhance the foundational reasoning ability of the base model, we explore two complementary approaches:

Text-Only Reasoning Enhancement: We utilize largescale and high-quality verifiable text-only data for rulebased RL. This approach leverages a wide variety of textbased reasoning problems, which are inherently more challenging and demand more complex reasoning processes compared to existing multimodal reasoning tasks. By training on these rich textual reasoning tasks, we aim to develop strong foundational reasoning capabilities for the model, which can be potentially transferred to multimodal contexts. Multimodal Reasoning Enhancement: As a comparison, we also utilize available multimodal verifiable data for rulebased RL training. While this data is more limited in the quality, this approach provides the model with direct exposure to the multimodal domain. As a result, it offers more immediate benefits for multimodal reasoning tasks and enhances the model's ability to understand visual contexts.

4.2. Multimodal Generalization Training (MGT)

After enhancing the foundational reasoning capabilities of the model, we focus on evaluating how well these capabilities generalize to diverse multimodal domains. We evaluate across two distinct domains that test different aspects of multimodal intelligence: General Multimodal Reasoning Domain and Agent-Related Reasoning Domain. By continuing RL training on these domains, we aim to improve the multimodal reasoning ability of the model.

4.2.1. General Multimodal Reasoning Domain

This domain focuses on the visual perception ability to perform reasoning based on both image contents and texts.

Visual Reasoning-Centric Geometric Domain (Geo): We select geometric reasoning as our first domain for continued RL training due to its natural bridge between our initial reasoning enhancement stage and multimodal applications. This domain shares structural similarities with the mathematical reasoning used in FRE stage while introducing visual perception challenges. By continuing RL training on geometric problems, the model learns to extract visual information and apply mathematical reasoning. This domain is relatively simple, as the model already possesses rich pretrained knowledge about geometric concepts, and the data distribution is similar to that of the FRE stage.

Perception-Reasoning Balanced Domain (PerceReason): For our second continued RL training domain, we employ a broad spectrum of multimodal tasks from over 20 distinct datasets that require more perception ability than geometric domain, including visual question answering, document understanding, mathematical reasoning, and scientific reasoning. This diverse training domain exposes the model to various visual contexts and reasoning problems simultaneously. By continuing RL training across this comprehensive collection, the model must adapt its reasoning capabilities to handle heterogeneous inputs and tasks-mirroring realworld application scenarios. This domain presents a moderate challenge since the model has rich pretrained multimodal knowledge, but the data distribution differs significantly from the FRE stage. This stage evaluates whether enhancing reasoning ability by FRE stage training builds a strong foundation model. The foundation model is expected to be efficiently transferred to various challenging multimodal domain via continued reinforcement learning.

4.2.2. Agent-Related Reasoning Domain

To evaluate and enhance the model's ability to act as an agent in complex visual environments, we follow MageBench [92] to evaluate the how well our enhanced reasoning capabilities transfer to tasks requiring sequential decision-making and planning in visual contexts. We select two domains from MageBench in the following.

Sokoban Planning Domain: Sokoban is a classic puzzle game that requires the agent to push boxes to designated target locations. This domain evaluates the model's spatial reasoning and planning capabilities, as it must visualize potential moves, anticipate deadlocks, and generate an optimal sequence of actions.

Football Game Domain: This domain places the model

Table 1. Results (%) across benchmarks categorized by three reasoning intensities: High-Level Reasoning (Text-Only) (MATH500/GPQA), Multimodal Reasoning (OlympiadBench/MathVision/MathVerse), and General Multimodal (MM-Star/MathVista). The "MM Avg" column displays the average performance across all multimodal benchmarks. The **best** result is **bolded** and the <u>second-best</u> is <u>underlined</u>.

Model	Text-Only			MM R	easoning-D	ominated	MM (MM Avg	
	MATH	GPQA	Avg	Olymp.	MathVis.	MathVer.	MM-Star	MathVista	
Qwen2.5-VL CoT	63.40	30.30	46.85	10.28	23.59	34.64	51.40	60.70	36.12
Foundational Reasoning Enhancement Stage									
FRE-Multi	61.80	27.27	44.54	11.80	24.74	38.45	58.76	64.20	38.71
FRE-Text	<u>65.40</u>	<u>36.87</u>	<u>51.14</u>	15.62	25.76	38.83	55.15	61.40	<u>39.35</u>
Multimodal Generalization Training Stage									
MGT-Geo	65.80	32.32	49.06	14.63	26.84	41.80	54.39	59.00	39.33
MGT-PerceReason	63.80	38.89	51.35	15.62	26.35	<u>41.55</u>	<u>58.03</u>	63.20	40.95

in a multi-agent football environment where it must control a player to achieve game objectives. The model needs to make strategic decisions based on the positions of teammates and opponents, demonstrating cooperation and interaction skills in a competitive setting.

In addition, we also continually train the model on Sokoban via rule-based RL to enhance the model's agent capabilities, further validating our approach's effectiveness in agent domains. Notably, these domains represent scenarios that the model has not encountered during pretraining and serve as a challenging test of generalization, as they have data distributions significantly different from our firststage rule-based RL training.

5. Experiments

In the experiments, we use Qwen2.5-VL-Instruct-3B [6] as our baseline model and apply LMM-R1 framework on it. First, by training the baseline model with rule-based RL in multimodal and text-only datasets respectively, we get the reasoning-enhanced foundation model: FRE-Multi and FRE-Text (FRE stage). Then we continue the rule-based RL training on the FRE-* model in other multimodal domains (MGT stage) and get the MGT-Geo, MGT-PerceReason model and MGT-Sokoban. Besides, we also train baseline model with rule-based RL by using the same datasets of different domains and name these models as Direct-RL-* (e.g., Direct-RL-Geo, Direct-RL-Sokoban) for comparison with our MGT-* models.

5.1. Setting and implementation details

Datasets: We use multiple datasets across different training stages in our experiments.

FRE Stage: We use the following datasets for the FRE stage to enhance the reasoning capability of the model: (1) **Text-Only RL Dataset:** We use the prompt-answer pairs from DeepScaler-Preview-Dataset [49], which contains 40k math prompt-answer pairs and all of them have

unique verifiable answers. (2) Verifiable Multimodal-65K (VerMulti): We use the MathV360K [64] dataset, which contains 360k multimodal problems with diverse domains, including arithmetic, geometry, calculus, science, and more. The dataset is further filtered, saving prompts that have verifiable numeric answers (e.g., 123, 4.11) or option answer (e.g., A, B, C, D). Finally, we get 130k multimodal problems. To reduce the cost of training, we randomly sample 65k data from the filtered dataset for rule-based RL training. MGT Stage: We continue training FRE-Text model with rule-based RL using different datasets for different domains. (1). Visual Reasoning-Centric Geometry Domain: We extract the geometry problems from Ver-Multi, collecting 15K geometry problems and getting the VerMulti-Geo. (2). Perception-Reasoning Balanced Domain: We directly use the VerMulti dataset. (3). Sokoban **Domain:** We follow [58] to randomly generate 11500 environments for sokoban game as our training set.

See implementation details in Appendix A.

5.2. Experiments Results

We evaluate the performance of the model from two main aspects: General Task Benchmarks in Sec. 5.2.1 and Agent-Related Benchmarks in Sec. 5.2.2. General Task Benchmarks focus on the model's fundamental capabilities in reasoning, visual perception, and multimodal understanding, which serve as the foundation for handling complex tasks. In contrast, Agent-Related Benchmarks concentrate on assessing the model's performance in planning, decisionmaking, and goal-oriented tasks, which are essential abilities for building intelligent systems capable of autonomous operation in real-world environments.

5.2.1. General Task Benchmarks

To comprehensively evaluate our models' capabilities, we conduct experiments across both multimodal and text reasoning benchmarks. For multimodal evaluation, we use five benchmarks as categorized in Tab. 1: OlympiadBench [24],

MathVision [75] test, and MathVerse [93] testmini for reasoning-dominated tasks, while MM-Star [12] and Math-Vista [47] testmini assess general multimodal capabilities. Complementing this, we evaluate pure reasoning abilities using MATH500 [36] and GPQA [59] datasets. MATH500 consists of 500 mathematics problems covering algebra, geometry, probability, and calculus, whereas GPQA comprises 448 multiple-choice questions in biology, physics, and chemistry authored by domain experts. This dual evaluation approach comprehensively assesses the reasoning ability of the model in various scenario ranging from basic text-only context and challenging multimodal context

Foundational Reasoning Enhancement Analysis Our evaluation across both multimodal and text-only reasoning benchmarks reveals distinct performance patterns between FRE-Multi and FRE-Text models, highlighting important trade-offs in multimodal model training.

On **Text-Only Benchmarks**, the divergence becomes even more pronounced. FRE-Text shows substantial improvements over the baseline, with a 2.0% increase on MATH500 and 6.57% on GPQA, resulting in a 4.29% overall enhancement in text-only performance. In contrast, FRE-Multi exhibits performance declines of 1.6% on MATH500 and 3.03% on GPQA, suggesting that training the model with relatively simple multimodal data may compromise its complex reasoning abilities, despite the improvement in visual reasoning ability.

On **Multimodal Benchmarks**, both models demonstrate improvements over the baseline Qwen2.5-VL, but with different strengths. For general multimodal tasks, FRE-Multi shows substantial gains with a 3.5% improvement on MathVista and 7.36% on MM-Star, while FRE-Text exhibits more modest improvements of 0.7% and 3.75%, respectively. This suggests that RL with multimodal data more effectively enhances general visual capabilities. Conversely, for multimodal reasoning-dominated tasks, FRE-Text demonstrates stronger performance with improvements of 5.34% on OlympiadBench, 2.17% on MathVision, and 4.19% on MathVerse, compared to FRE-Multi's smaller gains of 1.52%, 1.15%, and 3.81%, respectively.

These results reveal a fundamental trade-off: multimodal RL enhances vision-related capabilities but may compromise pure reasoning abilities, whereas text-only RL strengthens core reasoning capabilities that effectively transfer to multimodal reasoning contexts while providing more limited benefits for tasks primarily requiring visual perception. This performance dichotomy underscores the importance of training data selection in developing models with balanced capabilities.

Based on these findings, we select FRE-Text as our reasoning-enhanced foundation for subsequent experiments, as it provides the strongest foundational reasoning capabilities while maintaining competitive performance on multimodal tasks, offering the best platform for further domain-specific enhancement.

Multimodal Generalization Training Analysis

Geo Domain: We continue rule-based RL training on the VerMulti-Geo dataset to obtain the MGT-Geo model. As shown in Tab. 1, MGT-Geo surpasses the baseline by 3.21% on multimodal benchmarks, demonstrating strong multimodal capabilities.

To evaluate geometry-specific performance, we analyze results on geometry subsets from MathVision (categorized by mathematical geometry subfields: Analytic, Combinatorial, Metric, and Solid, which are the in-domain questions for VerMulti-Geo) and MathVerse (classified by visual dependency: from Text Domain to Vision Only). For comparison, we also train the baseline, Qwen2.5-VL, with the same VerMulti-Geo dataset by rule-based RL training method and get the Direct-RL-Geo, which skips the FRE stage. Results are presented in Tab. 2.

From Tab. 2, Direct-RL-Geo improves performance on simpler MathVerse tasks by 3.36% but decreases performance on more complex MathVision by 1.13% compared to the baseline, indicating limitations in developing robust reasoning through domain-specific training alone. While MGT-Geo achieves superior performance across all benchmarks, with significant improvements over FRE-Text on MathVision by 3.35% and MathVerse by 2.97%.

A particularly revealing finding emerges when examining the "Vision Only" category in MathVerse. Here, FRE-Text shows a 3.43% decline compared to the baseline, indicating that text-only reasoning enhancement may come at the cost of visual perception capabilities. However, MGT-Geo not only recovers but significantly enhances these capabilities, achieving an 8.25% improvement over the baseline and an impressive 11.68% improvement over FRE-Text. Interestingly, Direct-RL-Geo actually decreases performance in this category by 1.4%, further highlighting the importance of the FRE stage.

PerceReason Domain: Inspired by the success of the MGT-Geo model, we continue the rule-based RL training on the Perception-Reasoning Balanced Domain with Ver-Multi. The comprehensive benchmark results are shown in Tab. 1. The MGT-PerceReason model shows substantial performance improvements compared to FRE-Text, with an average increase of 1.6% across multimodal benchmarks.

This improvement is particularly pronounced in benchmarks that emphasize general visual tasks: the model achieves a 1.8% gain on MathVista and a 2.88% improvement on MM-Star. Notably, these enhancements in visual capabilities do not come at the expense of reasoning performance. In fact, MGT-PerceReason maintains or even improves upon the strong reasoning capabilities of FRE-Text across text-only and reasoning-focused benchmarks.

These results provide compelling evidence that our pro-

Table 2. Results (%) on geometry-related benchmarks. For MathVision, results are reported for Analytic/Combinatorial/Metric/Solid Geometry. For MathVerse, results are categorized by modality emphasis: TD (Text Domain)/TL (Text Lite)/VI (Vision Intensive)/VD (Vision Domain)/VO (Vision Only). The best performance in each subfield is bolded.

Model		MathVerse									
	Analy.	Combin.	Metric	Solid	AVG	TD.	TL.	VI.	VD.	VO.	Avg
Qwen2.5-VL CoT	34.52	20.78	26.33	20.49	25.53	43.15	35.41	33.38	32.87	28.43	34.64
Direct-RL-Geo	30.95	17.53	26.59	22.54	24.40	47.59	40.36	38.96	36.04	27.03	38.00
FRE-Text	28.57	22.08	31.01	24.10	26.44	48.22	42.26	39.72	38.96	25.00	38.83
MGT-Geo	36.90	22.73	31.66	27.87	29.79	51.02	42.51	39.72	39.09	36.68	41.80

Model

posed two-stage training framework creates a powerful synergistic effect. The FRE stage provides a stronger platform for domain-specific training, enabling simultaneous improvement in both reasoning and visual perception capabilities that cannot be achieved through either approach alone. By first enhancing fundamental reasoning capabilities through complex text-only data before introducing multimodal data, this approach effectively augments the model's performance on general visual tasks while preserving its core reasoning abilities. Importantly, this two-stage training strategy successfully circumvents the performance degradation in reasoning tasks that typically occurs when models are trained directly with multimodal RL data (as observed with the FRE-Multi model). The consistent improvements across diverse benchmarks demonstrate that FRE stage provides a more robust platform for developing multimodal models that excel in both perception-heavy and reasoning-intensive tasks, effectively boosting multimodal intelligence through an efficient training paradigm.

5.2.2. Agent Domain Generalization

One of the most intriguing applications for LMM is agents, which involves more complex reasoning. Specifically, it requires reasoning and perceiving interleaved process. We select Sokoban as a test scenario for rule-based RL training, as it is easy to scale and verify. The model is required to observe only the initial state and then, after deliberation, provide the complete sequence of actions in a single output. We randomly initialize 10,000 simple difficulty Sokoban levels and trained using the PPO algorithm. For comparison, MageBench [92] provides several environments and level settings for Sokoban that enable fair comparison. During training, as before, we use the rule-based task reward from MageBench, along with a minor format reward. The training results are shown in Tab. 3.

During testing, we evaluate not only the results of Sokoban-Global, which shares the same environment and agent settings as the training phase, but also test an unseen environment with completely different settings in MageBench, specifically the Football-Online results. The last block in Tab. 3 presents the original QwenVL-2.5 results, as well as the results from text-only training discussed

Sokoban-Global Football-Online Idle baseline 41.18 2.53 Human level 83.63 54.68

Table 3. Agent-level evaluation on MageBench-Sokoban and

Football environments. All values represent well-defined rewards.

Global setting: The model observes the initial scene once and

determines all subsequent actions. Online setting: The model ob-

serves the game scene and makes one action per time step.

Claude-3.5-Sonnet	48.26	16.94
Gemini-1.5-pro	46.13	18.33
GPT-40	46.09	21.20
Qwen2.5-VL-3B	42.35	15.36
FRE-Text	44.81 (+2.46)	18.46
Direct-RL-Sokoban	46.89 (+4.54)	16.32
MGT-Sokoban	47.91 (+5.56)	18.99

earlier. The results indicate that the reasoning capabilities derived from text-only training exhibit stable generalization in agent environments. Training within the corresponding in-domain environment can demonstrate further performance improvements. Using a model with only 3B parameters, after training, it can match or even surpass productlevel large models. This suggests that rule-based reinforcement learning may have significant potential applications in the fields of agent and embodied AI planning.

5.3. Discussion

Generalization Capability of RL Compared to SFT

To investigate the generalization capabilities of different training paradigms, we conduct a comparative analysis between RL and SFT approaches during the first training stage. For this experiment, we use identical text datasets, DeepScaler-40K [49], for both training methodologies. For the SFT approach, we first generate comprehensive reasoning processes for each query-answer pair using DeepSeek-R1-Distill-Qwen-14B [22], then employ these structured triplets, i.e., (query, reasoning process, answer), as training data to obtain SFT-Text. Subsequently, we fine-tune the SFT-Text model on the VerMulti-Geo dataset using rulebased RL to produce SFT-Geo. For the RL approach, we use FRE-Text and MGT-Geo as the comparative models to



Figure 3. Results (%) on geometry domain with SFT and RL.

SFT-Text and SFT-Geo, respectively.

We evaluate both training paradigms on general reasoning capabilities and geometry domain generalization performance, with results shown in Fig. 3. Our findings reveal that direct SFT with text data on the baseline model leads to significant performance degradation, exhibiting catastrophic forgetting [90]. In contrast, using the same data for RL training results in substantial performance improvements. Furthermore, when evaluated on downstream tasks, SFT-Geo begins to recover performance on geometry tasks, with overall downstream performance exceeding the baseline but still falling short of the RL model. These results demonstrate that compared to SFT, RL not only avoids catastrophic forgetting but also more effectively transfers reasoning capabilities to other domains.

Why Multimodal RL is not better than Text-only RL?

Our experimental results reveal a counterintuitive phenomenon: while multimodal RL training enhances perfor-



Figure 4. Response length trends of 3 models during RL training.

mance on multimodal benchmarks, it simultaneously leads to a decline in text-only reasoning capabilities compared to the baseline model. To elucidate this paradox, we conduct a detailed analysis of model behavior during the RL training process across different datasets, examining both output patterns and reasoning strategies.

We show the response length trending of models trained on different datasets exhibit striking divergence in Fig. 4. FRE-Multi shows a consistent downward trend in response length, decreasing from approximately 150 tokens at initialization to below 80 tokens after 120 training steps. In contrast, FRE-Text demonstrates rapid growth in response length during the initial training phase, rising from 600 tokens to over 800 tokens within the first 40 steps, after which it maintains a stable length around 800 tokens for the remainder of the training period. While MGT-PerceReason demonstrates a particularly interesting pattern in Fig. 4. After FRE stage training, its response length stabilizes between 200-250 tokens during subsequent multimodal training, maintaining a balance between reasoning depth and visual recognition efficiency.

Furthermore, we analyze sampled outputs across different training stages to elucidate this divergence. Comparing model outputs between the initial model and after 120 training steps reveals distinct patterns. The FRE-Multi model exhibits a clear trend toward brevity: while the initial model produces relatively detailed reasoning, by 120 steps it generates significantly condensed responses that directly identify visual elements with minimal reasoning steps, despite maintaining answer accuracy. Conversely, the FRE-Text model demonstrates the opposite trajectory: its responses after 120 steps become more elaborate compared to the initial model, incorporating additional reasoning steps, explicit mathematical formulations, and more comprehensive explanations. This pattern aligns with the quantitative length measurements presented in Fig. 4. Detailed examples of these contrasting behaviors are given in Appendix F.

The results suggest that the two-stage training strategy is a practical and advantageous approach for developing robust multimodal reasoning models, especially given the current scarcity of high-quality multimodal reasoning data.

6. Conclusion

We introduce LMM-R1, a framework designed to enhance multimodal reasoning in LMMs through rule-based RL. This is achieved via a two-stage strategy: Foundational Reasoning Enhancement (FRE) and Multimodal Generalization Training (MGT). Despite the initial limitations in reasoning capabilities of 3B LMMs, LMM-R1 substantially improves their performance. Experiments show that text-only reasoning establishes a solid foundation for multimodal generalization, creating a synergistic effect that outperforms models trained solely on text or multimodal data. In agent-related domains, LMM-R1 notably enhances performance in complex planning tasks. Future work involves extending our framework to additional LMMs and developing methods for synthesizing high-quality multimodal reasoning data for rule-based reinforcement learning.

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Appendix

A. Training Details

A.1. Datasets

Text-Only Dataset: We use DeepScaleR-Preview [49] as the text-only math reasoning dataset to train FRE-Text. This dataset is composed of AIME(American Invitational Mathematics Examination) problems (1984-2023), AMC (American Mathematics Competition) problems (prior to 2023), Omni-MATH [19] and STILL [72]. It is filtered to keep those that have verifiable answers and to remove redundant problems, leaving 40.3k high-quality data points.

VerMulti-65K: We use 65k verifiable problems filtered from MathV360K to train FRE-Multi, which consist of problems from various sources as shown in Tab. A4.

Split	Count	Split	Count
IconQA [44]	7166	TQA [29]	2130
PMC-VQA [94]	6760	DocVQA [52]	1974
TabMWP [46]	6732	TextVQA [65]	1462
A-OKVQA [28]	6185	VQA2.0 [21]	1316
FigureQA [27]	4995	ChartQA [51]	1115
ScienceQA [45]	4243	PlotQA [53]	1020
GeoQA+ [8]	4062	Super-CLEVR [35]	1016
DVQA [26]	3317	VQA-AS [2]	404
Geometry3K [43]	2845	MapQA [9]	278
UniGeo [10]	2767	VizWiz [23]	204
AI2D [28]	2603	GEOS [61]	129
CLEVR-Math [38]	2393	VQA-RAD [32]	2

Table A4. Statistics of VerMulti.

VerMulti-Geo15K: We use 15k geometry problems from MathV360K [64] to train MGT-Geo, which consists with GEOS [61], Geometry3K [43], GeoQA+ [8], UniGeo [10], and TQA [29]. The distribution of data is shown in Tab. A5.

Sokoban Training Datasets: For the Sokoban domain, we generated a diverse set of 11,500 environments by using gym-sokoban [58] with varying difficulty levels to train MGT-Sokoban. Specifically, we created 5,000 environments using the sokoban-small-v0 difficulty setting and another 5,000 environments with sokoban-small-v1 difficulty. To ensure the model encounters a wide range of scenarios, we further supplemented the dataset with 500 environments each from sokoban-v0, sokoban-v1, and sokoban-large-v0 difficulty settings. This distribution allows the model to learn planning strategies across different board sizes and complexity levels, from simpler small-scale puzzles to more challenging large configurations.

Split	Count
GEOS	271
GeoQA+	8155
Geometry3K	2776
TQA	25
UniGeo	5583

Table A5. Statistics of VerMulti-Geo15K.

A.2. Training Hyper-Parameters

Our training infrastructure is built upon OpenRLHF [25], and we use the same set of hyper-parameters for RL, as shown in Tab. A7.

We train SFT-Text 2 epochs with batch-size=256, learning-rate=5e-6, warmup-ratio=0.03.

B. Detailed Performance on MM-Star

To validate the improvement of our model on general visual tasks, we also provide the MM-Star different split results in Tab. A6. The results show that MGT can improve the perception ability of FRE-Text.

Model	Coarse	Fine-grained	AVG
QwenVL-2.5 CoT	68.56	47.52	58.04
FRE-Multi	69.32	52.05	60.68
FRE-Text	65.20	46.30	55.75
MGT-PerceReason	67.99	48.19	58.09

Table A6. Performance comparison (%) on different perception categories in MM-Star benchmark. Coarse Perception includes tasks requiring basic object recognition, while Fine-grained Perception involves more detailed visual discrimination tasks.

C. Evaluation Details

C.1. Text-Only Benchmarks

We use LightEval [18] to evaluate our models on textonly mathematical reasoning benchmarks. LightEval is a lightweight evaluation framework that provides standardized evaluation protocols for language models. For our evaluation, we focus on two challenging mathematical reasoning benchmarks: MATH-500 [36] and GPQA-Diamond [59].

Evaluation Protocol. We implement custom evaluation tasks within the LightEval [18] framework to ensure consistent and reproducible evaluation. For each benchmark, we define specific prompt templates that encourage step-by-step reasoning and clear answer formatting, as shown in

	FRE-Text	FRE-Multi	MGT-Geo	MGT-PerceReason	MGT-Sokoban
train_batch_size	128	256	256	256	128
rollout_batch_size	128	256	256	256	128
temperature	1	1	1	1	1
n_samples_per_prompt	16	16	16	16	16
max_epochs	1	1	1	1	1
num_episodes	1	2	2	2	4
generate_max_len	8192	8192	8192	8192	8192
init_kl_coef	1e-3	1e-3	1e-3	1e-3	0.0
lambd	1	1	1	/	1
gamma	1	1	1	/	1
actor_learning_rate	1e-6	1e-6	4e-7	4e-7	1e-6
critic_learning_rate	9e-6	9e-6	9e-6	/	5e-6
warm-up ratio	0.03	0.03	0.03	0.03	0.03

Table A7. Training Hyper-parameters.

Appendix E. The evaluation is conducted with a maximum generation length of 32,768 tokens to accommodate extensive reasoning chains.

Metrics. For MATH-500, we employ a specialized metric that extracts answers from LaTeX expressions, with priority given to boxed answers. This metric uses multilingual extractive matching with a precision of 5 decimal places. For GPQA-Diamond, we use a letter-based extraction metric that identifies the selected multiple-choice option (A, B, C, or D) from the model response.

Both metrics are implemented using LightEval's multilingual extractive match framework, which provides robust answer extraction capabilities even when models deviate slightly from the requested output format. This approach ensures fair comparison across different model architectures and response styles.

C.2. Multimodal Benchmark

We use LMMs-Eval [91] for multimodal benchmark evaluation, which is a comprehensive and lightweight evaluation toolkit for LMMs. We evaluate our models in representative challenging multimodal reasoning benchmarks, including MathVision [75], MathVerse [93], MathVista [47], OlympiadBench [24] and MM-Star [12].

Evaluation Protocol. We integrate vLLM [31] into LMMs-Eval and deploy our models on vLLM for efficient evaluation. To accurately extract the answer of the model for each test case, we deploy Qwen2.5-14B-Instruct [70] as a judge, using the prompt shown in Appendix **E**.

The system prompts of our models used in training and evaluation are the same, which are also listed in Appendix \mathbf{E} . Furthermore, we find that using the same system prompt for the baseline model degrades its performance. Thus, for fairness, we do not use our system prompt for the baseline model.

C.3. Agent-Related Benchmark

We follow the MageBench [92] to evaluate our model in Sokoban and football tasks.

Agent Formulation. We use two agent designs from MageBench [92] for our evaluations:

Global Planner Agent: This agent observes the initial environment once and plans all subsequent actions without further observations. Its decision process is:

$$\pi_{\theta}(p_{sys}, p_{task}, p_{cot}, p_{io}) \to a_1, a_2, \dots, a_T$$
(A2)

Online Planner Agent: This agent analyzes each step and acts based on previous actions (AM) and observations (OM). We set AM = 5 and OM = 1. Its decision process is:

$$\pi_{\theta}(p_{sys}, a_{t-AM:t}, o_{t-OM:t}, p_{cot}, p_{io}) \to a_{t+1} \qquad (A3)$$

Task Descriptions.

- **Sokoban-Global:** The model sees the initial puzzle once and plans all moves in advance. This tests the model's ability to mentally simulate the environment.
- Football-Online: The model controls a player in a dynamic environment, making decisions based on changing game states. This tests real-time decision-making in complex scenarios.

D. Training Curves



Figure A6. Training Curve of FRE-Multi.







Figure A8. Training Curve of MGT-PerceReason.

E. Prompts for Training and Evaluation

System Prompts for Training and Evaluation

You are a helpful assistant good at solving math problems with step-by-step reasoning. You should first thinks about the reasoning process in the mind and then provides the user with the answer. Your answer must be in latex format and wrapped in \$...\$.The reasoning process and answer are enclosed within <think> </think> and <answer> </answer> tags, respectively, i .e., <think> Since \$1+1=2\$, so the answer is \$2\$. </think><answer> \$2\$ </answer>, which means your output should start with <think> and end with </answer>.

Prompt Templates for Text-Only Benchmarks

Solve the following math problem efficiently and clearly. The last line of your response should be of the following format: 'Therefore, the final answer is: \becad{ANSWER} . I hope it is correct' (without quotes) where ANSWER is just the final number or expression that solves the problem. Think step by step before answering.

{Question}

Answer the following multiple choice question. The last line of your response should be of the following format: 'Answer: \$LETTER' (without quotes) where LETTER is one of ABCD. Think step by step before answering.

{Question}

- A) {A}
- B) {B}
- C) {C}
- D) {D}

Prompt of Answer Extraction for Qwen2.5-14B-Instruct

Please	read	the	following	example.	Then	extract	the	answer	from	the	model	response	and	type	it
at	the	end (of the prom	npt.											

Hint: Please answer the question requiring an integer answer and provide the final value, e.g., 1, 2, 3, at the end.

Question: Which number is missing?

Model response: The number missing in the sequence is 14.

Extracted answer: 14

Hint: Please answer the question requiring a floating-point number with one decimal place and provide the final value, e.g., 1.2, 1.3, 1.4, at the end. Question: What is the fraction of females facing the camera?

Model response: The fraction of females facing the camera is 0.6, which means that six out of ten females in the group are facing the camera.

Extracted answer: 0.6

Hint: Please answer the question requiring a floating-point number with two decimal places and provide the final value, e.g., 1.23, 1.34, 1.45, at the end. Question: How much money does Luca need to buy a sour apple candy and a butterscotch candy? (Unit: \$)

```
Model response: Luca needs $1.45 to buy a sour apple candy and a butterscotch candy.
Extracted answer: 1.45
Hint: Please answer the question requiring a Python list as an answer and provide the final list
    , e.g., [1, 2, 3], [1.2, 1.3, 1.4], at the end.
Question: Between which two years does the line graph saw its maximum peak?
Model response: The line graph saw its maximum peak between 2007 and 2008.
Extracted answer: [2007, 2008]
Hint: Please answer the question and provide the correct option letter, e.g., A, B, C, D, at the
     end.
Question: What fraction of the shape is blue?\A 3/11\A 3/11\A 0
Model response: The correct answer is (B) 8/11.
Extracted answer: B
Hint: Please answer the question and provide the correct option letter, e.g., A, B, C, D, at the
     end.
Question: {question}
Model response: {response}
Extracted answer:
```

F. Case Study

```
Case Study of Qwen2.5-VL CoT and FRE-Text
```

Question: Find the sum of all real solutions to the equation $\frac{x-2}{x^2+4x+1} = \frac{x-5}{x^2-10x}$.

```
Qwen2.5-VL CoT:
```

```
Rearrange equation: divide by x^2 and let's use partial fractions to simplify the equation.
To simplify, write each fraction as a difference: $1 + \frac{x-4}{(x+2)(x+2)(x-5)} = 1 + \frac{(
            x-2) - (x-5)}{x^2-10x}$.
3. 2x^2 - 4x - 16 = 0.
4. Add 16 to both sides: 2x^2 - 4x = 0
5. Divide by 2: x^2 - 2x = 0.
6. Take out x: x(x-2) = 0. Elie: x = 0 or x = 2.
Therefore, the sum of all real solutions to the equation is x = 0 + 2 = $\boxed{2}$.
```

FRE-Text:

```
<think>

To solve the equation \(\frac{x-2}{x^2+4x+1} = \frac{x-5}{x^2-10x}\), we first eliminate the

denominators by cross-multiplying:

\[

(x-2) (x^2-10x) = (x-5) (x^2+4x+1)

]

Expanding both sides, we get:

\[

x^3 - 10x^2 - 2x^2 + 20x = x^3 + 4x^2 + x - 5x^2 - 20x - 5

]
```

```
Simplifying both sides, we have:
\[
x^3 - 12x^2 + 20x = x^3 - x^2 - 19x - 5
\backslash ]
Subtracting (x^3) from both sides, we get:
\[
-12x^{2} + 20x = -x^{2} - 19x - 5
\backslash ]
Rearranging all terms to one side, we have:
\[
-12x^{2} + x^{2} + 20x + 19x + 5 = 0
\setminus]
Simplifying further, we get:
\[
-11x^2 + 39x + 5 = 0
\]
This is a quadratic equation in the form (ax^2 + bx + c = 0), where (a = -11), (b = 39),
    and (c = 5). The sum of the solutions of a quadratic equation (ax^2 + bx + c = 0) is
    given by (-\frac{b}{a}). Therefore, the sum of the solutions is:
\[
- \{39\} \{-11\} = \{39\} \{11\}
\]
We need to check if the solutions satisfy the original equation and the denominators. The
    solutions to the quadratic equation are:
\[
x = \frac{-39 \m \sqrt{39^2 - 4(-11)(5)}}{2(-11)} = \frac{-39 \m \sqrt{1521 + 220}}{-22} = \sqrt{-22}
    frac{-39 \pm \sqrt{1741}}{-22}
\setminus 1
The solutions are:
\[
x = \frac{39 \mp \1741}{22}
\]
We need to ensure that these solutions do not make the denominators zero. The denominators are
    (x^2 + 4x + 1) and (x^2 - 10x). Substituting (x = \frac{39 \text{mp} \sqrt{1741}}{22}) into
    these denominators, we check:
For \langle x^2 + 4x + 1 \rangle:
\[
\left(\frac{39 \mp \sqrt{1741}}{22}\right)^2 + 4\left(\frac{39 \mp \sqrt{1741}}{22}\right) + 1 \
    neq 0
\setminus 1
For \langle x^2 - 10x \rangle:
\[
\left(\frac{39 \mp \sqrt{1741}}{22}\right)^2 - 10\left(\frac{39 \mp \sqrt{1741}}{22}\right) \neq
     0
\]
```

```
Since the solutions do not make the denominators zero, they are valid. Therefore, the sum of all
    real solutions is:

\[
\boxed{\frac{39}{11}}
\]
</think><answer> $\frac{39}{11}$ </answer>
```

Case Study of Qwen2.5-VL CoT and FRE-Text

Question: How many positive integers b have the property that $\log_b 729$ is a positive integer?

Qwen2.5-VL CoT:

We need to find positive integers \$b\$ such that $\log_b 729$ is a positive integer. This means that $b^{10}_{10}_{10} = 729$.

Let's find the prime factorization of 729. We have $729 = 3^6$.

We know that if $\log_b 3^6$ is a positive integer, then \$b\$ must be a power of 3. Let's write $b = 3^x$. Then we have $\log_{3^x} 3^6 = 2$ \$ since $b^q = 3^6$ \$ implies that $3^{x} \setminus c$ $\log_{3} 3^6$ = 3^6 \$ and $\log_{3} 3^6 = 6$ \$. Thus, we have $x \setminus c$ $\log_{3} 3^6 = 6$ \$. This simplifies to $x \setminus c$ f = 6\$, so x = 1\$.

This means $b = 3^1 = 3^{\circ}$ is a solution. We need to check other powers of 3, but since $\log_{3} = 6^{\circ}$, any other power of 3 greater than 3 would result in a non-positive integer for $\log_{b} 729^{\circ}$. Therefore, there is only one positive integer b° for which $\log_{b} 729^{\circ}$ is a positive integer.

The answer is: 1

FRE-Text:

```
<t.hink>
To determine how many positive integers (b ) have the property that (\log_b 729) is a
    positive integer, we start by letting ((\log_{b} 729 = k)), where (k ) is a positive
    integer. This equation can be rewritten in its exponential form as:
[b^k = 729]
We need to find all possible values of ( b ) such that ( 729 ) is a perfect power of ( b )
    . First, we factorize (729 ):
[729 = 3^{6}]
For (b^k = 3^6 ) to hold, (b ) must be a power of (3 ). Let (b = 3^m ), where (m )
    \) is a positive integer. Then we have:
[ (3^m)^k = 3^{6k} ]
This implies that (( m \cdot k = 6 \). We need to find all pairs (((m, k))) such that (( m \cdot
     k = 6 \setminus). The possible pairs \setminus ((m, k) \setminus) are:
1. ((1, 6))
2. \( (2, 3) \)
3. \( (3, 2) \)
4. \( (6, 1) \)
For each pair ((m, k)), we can find (b ):
1. If \langle m = 1 \rangle and \langle k = 6 \rangle, then \langle b = 3^1 = 3 \rangle.
2. If \langle m = 2 \rangle and \langle k = 3 \rangle, then \langle b = 3^2 = 9 \rangle.
```

3. If (m = 3) and (k = 2), then $(b = 3^3 = 27)$. 4. If (m = 6) and (k = 1), then $(b = 3^6 = 729)$.

Thus, the possible values of (b) are (3, 9, 27,) and (729). There are 4 such values.

```
Therefore, the number of positive integers \( b \) that have the property that \(\log_{b} 729\) is a positive integer is:\[\boxed{4}\]</think><answer> $4$ </answer>
```

Case Study of Qwen2.5-VL and FRE-Multi

Question: What is the median number of points scored by the team per game? **Points per game**

Stem	Leaf
2	04
3	45
4	9
5	678
6	066
7	56
8	0455
9	0

Qwen2.5-VL:

```
<t.hink>
Step 1: Identify all the data points in the stem and leaf plot.
From the stem and leaf plot, the points per game are as follows:
- 21
- 24
- 34, 35
- 49
- 56, 57, 58
- 66, 66
- 75, 76
- 84, 85, 85, 85
- 90
Step 2: Arrange the data points in ascending, descending or random order.
The points in ascending order are:
21, 24, 34, 35, 49, 56, 57, 58, 66, 66, 75, 76, 84, 85, 85, 85, 90
Step 3: Find the median.
Since there are 17 data points (an odd number), the median is the middle number when ordered.
In this case, the 9th number in the ordered list is the median.
The 9th number is 56.
Therefore, the median number of points scored per game is 56.
</think><answer> $\\boxed{56}$ </answer>
FRE-Multi:
<think>
To find the median, I need to follow these steps:
```

```
1. List all the values in ascending order.\n2. Identify the middle value(s).
```

Case Study of Qwen2.5-VL v.s. FRE-Multi

Question: What is the value of 'legs' for 'grade'?



Qwen2.5-VL:

<think> To find the value of 'legs' for 'grade', we need to look at the legend of the graph, which clearly indicates that 'legs' are represented by the blue circles. After identifying the data for \"grade\" in the graph, we see that the corresponding value for 'legs' is 4. Therefore, the value of 'legs' for 'grade' is 4.\n

FRE-Multi:

<think> The 'legs' value for 'grade' is shown on the bar chart as 4. </think><answer> $\$ (4)\$ </answer>

Case Study of Qwen2.5-VL and FRE-Multi

Question: How many vehicles in the image have wheels?



Qwen2.5-VL:

<think>

First, I'll identify each vehicle in the image. There is a double bus (blue), a car (tan), a car (yellow), a motorcycle (green), a scooter (cyan), and an airplane (gray). Some of these are likely to have wheels.

Now, examining the vehicles one by one:

- The blue double bus typically has wheels.
- The tan car and the yellow car have wheels.
- The green motorcycle has two wheels.
- The scooter likely has two wheels as well.
- The gray airplane typically has small wheels beneath.

When considering this categorically, all of these vehicles seem to have wheels. However, classifying vehicles as always having wheels or as having potential wheels introduces subjectivity. Typically most vehicles have wheels unless otherwise specified, so I'll make conservative assumptions regarding certainty.

I'll perform a count suggesting the vehicles have wheels:

- 1. The double bus has wheels.
- 2. The cars each usually have wheels.
- 3. The motorcycle presumably has wheels.
- 4. The scooter likely has typical two wheels.
- 5. The airplane typically has wheels.\n\nThus, I will count the potentially wheel-related vehicles (assumed to have wheels before explicit confirmation):
- </think><answer> \$\\boxed{4}\$ </answer>

FRE-Multi:

<think> We need to count the number of vehicles with wheels in the image. Let's identify them: 1. The blue bus has wheels. 2. The green motorcycle has wheels. 3. The brown sedan has wheels. 4. The yellow sedan has wheels. 5. The cyan scooter has wheels. 5. The cyan scooter has wheels. There are no other vehicles with wheels in the image. Therefore, the total number of vehicles with wheels is 5.

Case Study of Qwen2.5-VL and FRE-Multi

Question: What is the purpose of the left lane in the picture? Choices:

- (A) To show the results of immunofluorescent labeling
- (B) To indicate the upper layer of synovial membranes
- (C) To show the magnification of the image
- (D) To display the results of immunohistochemistry



Qwen2.5-VL:

<think> The image appears to be a microscope slide of tissue sections. The left lane consistently showing up in the micrograph suggests that it is used to display the results of immunohistochemistry, where antibodies are applied to stained tissue sections to detect specific molecules. The other options do not align with the visual presentation and technical names associated with immunohistochemistry. </think><answer> \$\\boxed{D}\$ </ answer>

FRE-Multi:

<think> The presence of the arrow and the context suggest that the left lane is used to display the results of immunchistochemistry. </think><answer> \\boxed{D} </answer>